

Print ISSN: 0022-2755

Journal of Mines, Metals and Fuels

Contents available at: www.informaticsjournals.com/index.php/jmmf

PLC Controlled Assembly Automation for Spot Welding Work Station

C. V. Dhanalakshmi^{1*} and B. S. Shivashankara²

¹*Student, M. Tech in Industrial Automation and Robotics, Malnad College of Engineering, Hassan - 573202, Karnataka, India; dhanalakshmicv99@gmail.com*

²*Assistant Professor, Department of Mechanical Engineering, Malnad College of Engineering, Hassan - 573202, Karnataka, India; sbs@mcehassan.ac.in*

Abstract

Automation has created an eminent need in the present trend of manufacturing industries to boost its throughput with reduced manual intervention and benefit in terms of good product quality, reduced scrape rate, and efficient usage of resources. Assembly process necessitates more perfection to achieve good quality products, which can only be possible by employing highly skilled and experienced operators which costs more and hence Automation is the best choice to mitigate this problem. The present work is an effort to upgrade the manual assembly station for spot welding process to assemble three sub-components called cup, fastener and mesh together through spot welding process with an automatic part handling mechanism, controlled by sensor-based Programmable Logic Controllers (PLCs). The automated assembly station resulted in flaw less welded components with reduced cycle time, which enhanced the assembly process productivity from 2 parts/min to 6 parts/min.

Keywords: Automated Assembly Line, PLC Controller, Spot Welding.

1.0 Introduction

Automation is a trend of science where a process is accomplished according to the previously set programs with minimum human intervention¹. Automation is an integration of Mechanical elements with Control Technology which has an ability to carry out the process with minimum human intervention². There are mainly few basic elements of automation in control system to actuate, generate power, set of programming instructions and sense feedback from the devices through transformation process. The control system may include Programmable Logic Controller, relay systems, Human Machine Interface³. The Electro pneumatic systems and electrical devices like Motors, Solenoid are belonged to actuating system. The feedback system is very essential

*Author for correspondence

to check some of decision made and to minimize the deviation of system⁴.

1.1 Some of the Project Works Done by Some of the Industry Experts

Umesh S. Patharkar and J.J. Salunke, explains the automation importance for less human intervention by previously set programs¹. Michael J. McDonald. The authors identify the user communication for the better implementation of the various automation mechanization². Sonja Stork, Christian Stossel, Anna Schubo explains useful control systems in automation and their application which includes Programmable Logic Controller, relay systems, Human Machine Interface³. Mohd Javaid *et al.* In this paper industry's strengths and applications are explained⁴. Gunter Reinhart *et al.* This paper explains that implementing multi-station assembly lines also improves

accuracy, provides a stable process, and increases product variants⁵. Cosima Stocker et al. In this paper, the author explains the development of an automated orienting device. Without any human effort parts can be segregated based on their shape and orientation⁶. Chitransh Singh, M.L. Chandravanshi explains the importance of vibratory feed bowler in manufacturing industry, bowl mechanism, working and what are the concepts need to control in vibratory bowl mechanism7. Minghai Yuan et al. This technology is rapidly used because of its speed of welding, less consumption of energy, and the precision of the component will be more. Precision control and safety are high by adopting the Siemens-controlled welding system⁸. Shyamjith Uralath et al. automatic spot-welding method which leads to efficient products with less cycle time in mass production with more safety9. Mallikarjun G. Hudedmani et al. This paper discussed the previous mechanization and today's automation technologies to recognize and improve PLC application in any sector¹⁰.

2.0 Methodology

2.1 PLC Controlled Assembly Automation for Spot Welding Work Machine

The assembly line is a complete system that consists of vibratory bowl feeder, servo press, carousal, conveyor and spot-welding machine which are all operating by the PLC controlling system through human machine

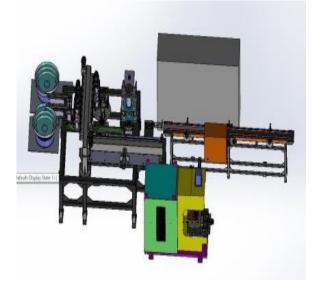


Figure 1. Proposed layout assembly station.

interface⁵. This assembly station takes the child parts (cup, fastener and mesh) as input. The main objective of this project is toautomate the part assembly and welding by reducing the manpower, increase the production rate with more repeatability so as to increase the production capacity.

3.0 Vibratory Bowl Feeder

A bowl feeder is a mechanism used for supplying small parts like a cup and fastener to a production line for sorting bulk items for rapid use. It uses mechanical vibrations to move the parts from the bowl feeder to the nextoperation⁷. Here linear motion step bowl feeder system is used which sets on a spring- loaded base that moves vertically. Step bowl feeders are capable of arranging, selecting, feeding, and sorting parts for the operation. Bowl feeders are a practical way to eliminate manual labor costs. The bowl diameter is the central element of the process. The feeder system's base unit serves as its driving unit. It is chosen in accordance with the feeding materials, which take into account their dimensions, weight, length, and the number of pieces that will fit inside the bowl. Bowls are typically made from cast aluminum and stainless steel. These factors are controlled by a variable speed controller with a normal electrical supply. The vibratory bowl feeder is controlled by the amplitude controller7. To stabilize the motor speed, it has an electromagnetic field.



Figure 2. Vibratory Bowl Feeder.

4.0 Spot Welding Machine

Spot welding is used to weld mesh to the cup by applying the heat which is necessary for welding. It is operated by resistance to the flow of current through the electrode⁸. The electrode is made of copper and copper is a good conductor of electricity. Here the electrode is fixed where



Figure 3. Spot Welding Machine.

Elite 20230204 > PLC 1 (CPU 15125P-1 PN) > Pro

the current passes for the welding operation. Once the assembly and the ring stacking are finished the part moved to the conveyor. Then the operator picks up the component and places it on the work table. By using the clamps, tighten the component on the work table. The recipe will be already fed to the system by selecting the recipe, the operation will start as the slideway will start to move. Here the component needs six spots on the mesh, the current will pass through the electrode as per the requirement, the recipe will be fed on the system electrode will move down, and perform a weld on the required spot-on mesh. Then the electrode moves upwards and the slide moves again the electrode will move downwards and make another weld on the mesh like this the operation will continue up to six spot welding. The sensor is present on the slideway where if any human interaction is made then the operation will stop itself. A dresser unit is present on the machine for the dressing of the electrode. After that, the component will be take-off from the machine by the operator and the operation cycle carries out⁹.

5.0 PLC Program for the Application

PLC programmable logic controller is a system with customized instructions for performing a particular

र्स्ते ।	M 🖻 :	2 🔍 🗄 🗖 🕯	= 🖻 🛚 ±	@ 1 8 1 5	😰 🧐 🚱	總 🥸 🦻	⊊ ! <u>=</u> ' <u>=</u> €	Elockio									į,
																	-
		- ⊡	t														
	lock title mment	: "Main Program S	Sweep (Cycle)	·												-	^
0																	
•		k 1: CALL MANUA	WL .														
	Commer	11															
- 1	_	7/FC1			FC2	_	%FC19 FC_GENERAL &										
- 1		"FC_INTERLOCK"			outputs		SCALING										=
ŀ	EN		ENO	EN	1	ENO EN		ENO									
- 1		%FC5		%FC3	%FC4		%FC7	%FC12									
- 1		"FC_MANUAL"		"FC_ALARM"	"FC_SER		HOME"	"FC_RECIPE"									
l	EN		ENO	EN ENO	EN	ENO - EN	ENO	EN ENO									
- 1		Sirco			8°C9		%rC14			%r ca			%rC10				
	EN	"TC_AUTO OP10"	ENO	_	ЛО OP20*		TIC_AUTO O			CAUTO WALKING	ENO -	_	C_AUTO CAROUR	ENO			
_ [EN		ENG			ENG - EN		ENG	EN		END	EN		END	•		
1																	
•	Networ	k 2: BLINKER															
	Commer	nt															
1				"DB_TMER".													
- 1				"BLINK ON"													
- 1	"Alway:		TMER".	TON													
ŀ	-i		л <u> </u>	- IN Q -													
- 1			T# 250MS -	PT ET	T#Oms												
- 1				'DB_TMER'.													
-				TRUNK OFF										1005			-

Figure 4. Main Program for the Assembly Line.

_ III II X

전 양 양 특히 본 점 표준 점 : 점 : 점 : 점 : 점 : 점 : 점 : 점 : 점 : 점	
Biolinedee	
49-00- 🗇 🖬 🖬 🎜	
Network 2: BLERER	
Comment	
'08_TMER'.	
"EUNK ON"	
SM1.2 "De_mxes". YON "AlwaysTRUE" "BLINK OFF".Q Time	
T#250MS - PT ET - T#0ms	
'09_TMER'.	
"BUNK OFF"	
"DO_TIMER". TON	
"SLIK ON".Q Time	
19.250MS - FT ET - 19.0ms	
letwork 3: SPOTWELDING 1	
amment	
WC13 WC11	
"FC_SPOTWELDING STATION 1" "FC_SWM_SERVO"	
EN ENO ENO	
Retwork 4: SPOTWELDING 2	
lamment.	

Figure 5. Spot Welding PLC Program.

task. PLCs are used in industrial control systems for a wide variety of applications¹⁰. PLCs are useful tools for repeatable processes because repetitively performing a single task while monitoring the conditions.

6.0 Result



Table 1. Comparison of Manual and Automation ProcessResult

Result	Manual	Automation		
Production capacity	Less 2parts/min	High 6parts/min		
Safety	Less	High		
Manpower requirement	High	Less		
Wastage	More	Low		

Table 2. Result Analysis

7.0 Conclusion

Assembly Line Automation with Spot Welding Machine is carried out successfully. After executing the whole operation, it is confirmed that all the specification meets the requirement and the machine isready for production. Manual assembly and welding lead to some flaws where it affects the production results by consuming more time. To overcome this situation automation is installed. Because of this structure, the whole system runs without any troubles, and also the parameters like a high production rate with more safety, less wastage, low manpower involvement, less cycle time, and a more efficient product can be achieved. The production rate increased from 2 parts per min to 6 parts per min and also reduced the reworkand rejection of the assembled and welded parts. PLC controlled assembly automation for spot welding work station application is ideal for use in mining to repair and operate machinery and equipment, as well as to create new structures.

8.0 References

1. Patharkar US, Salunke JJ. Automation techniques and its industrial application: a review. Int J Res Aeronaut Mech Eng. 2016 May; 4(5):16-23.

- 2. McDonald MJ. Active research topics in human machine interfaces. sandia natl laboratories. 2000 Dec.
- Stork S, Stossel C, Schubo A. Optimizing humanmachine interaction in manual assembly. RO-MAN 17th IEEE Int Symp Robot Human Interactive Commun. 2008.
- 4. Javaid M, Haleem A, Singh RP, Rab S, Suman R. Significance of sensors for industry 4.0: Roles, capabilities, and applications. Sensors Int J. 2021; 2.
- 5. Reinhart G, Hammerstingl V, Leiber D, Weib F. Automated design of multi-station assembly lines. CIRP Conf. 2019 Jan; 79(2):137-142.
- 6. Stocker C, Reinhart G. Sensitivity analysis of the dynamic behavior of transported material in vibratory bowl feeder. Appl Mech Mater. 2016 June; 840:107-113.
- 7. Singh C, Chandravanshi ML. Study of vibratory bowl feeder: a review. IIT Dhanbad. 2018 Feb.
- Yuan M, Huang W, Zhang X, Tian S. Design of welding control system based on Siemens PLC. J Phys Conf Ser. 2019 Oct; 1314(1).
- Uralath S, Singh HR. Selection and applications of automatic spot-welding methods. IOSR J Mech Civil Eng. 2014 Jan; 11(4):50-54.
- 10. Hudedmani MG, Umayal RM, Kabberalli SK, Hittalamani R. Programmable Logic Controller (PLC) in Automation. Adv J Grad Res. 2017 Jul; 2(1):37-45.